



**GRANT N°: 871153** 

**PROJECT ACRONYME:** JERICO-S3

PROJECT NAME: Joint European Research Infrastructure for Coastal Observatories -

Science, services, sustainability

COORDINATOR: Laurent DELAUNEY - Ifremer, France - jerico-s3@ifremer.fr

	JERICO-S3 MILESTONE											
Joint Europea	n Research Infrastructure network for Coastal Observatory											
	Science, Services, Sustainability											
MS#, WP# and full	JERICO-S3 MS.26 - WP5 - "Considerations for SOP development of a WASP											
title to be provided to WP7"												
E Voy words	Environmental DNA, automated sample processor, molecular sensor,											
5 Key words	qPCR, ecogenomic sensor											
Lead beneficiary	AZTI											
Lead Author	Naiara Rodríguez-Ezpeleta											
Co-authors	Oriol Canals, Anders Lanzen											
Contributors	Dominique Durand, Catherine Dreanno, Laurent Delaunay, Veronique											
Contributors	Creach, Fabrice Not, Julien Mader											
Submission date 12 July 2023												

#### → Please specify the type of milestone:

	Report after a workshop or a meeting (TEMPLATE A)
	Report after a specific action (TEMPLATE B) (test, diagnostic, implementation,)
	Document (TEMPLATE B) (guidelines,)
Χ	Other (TEMPLATE B) (to specify) TABLE

Diffusion list			
Consortium beneficiaries	Third parties	Associated Partners	other

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# A) TEMPLATE B - Other cases (not a workshop or meeting report)

## 1.B - Objectives

To compile a table with the existing automated DNA samplers, so that a diagnostic of the potential and drawbacks of each type can be drawn.

## 2.B and implementation process

A bibliographic search was performed to identify these scientific publications reporting development and/of use of automatic DNA samplers and analysis devices.

### 3.B - Main report

(see table in next page)

Paper / link	Year	Insitut e	Type of study	Organisms targeted	Autonomou s sampling equipment / device	Samplin g capacity	In- device storage	Molecular profiling or biosensor s on device	Device readiness and use in monitoring	In-lab analysis	Summary of results
Jones et al. (2008) A robotic molecular method for in situ detection of marine invertebrate larvae. https://doi.org/10.1111/j.1471-8286.2007.02021.x	2008	MBARI	Larvae monitoring proof of concept	Invertebrate spp.	Moored ESP	Continou s	-	SHA for 5 invertebrat e spp.	ESP commerciall y available	Valdiatio n	SHA profiles validated by lab- based assays
Scholin et al. (2009) Remote Detection of Marine Microbes, Small Invertebrates, Harmful Algae, and Biotoxins using the Environmental Sample Processor (ESP). Oceanography. https://doi.org/10.5670/oceanog.200 9.46	2009	MBARI	Technical development	(depends on configuratio n)	1G? and Deep ESP	Varies with specs	RNALate r	SHA and ELISA	ESP commerciall y available (see above)	-	
Preston et al. (2011) Underwater Application of Quantitative PCR on an Ocean Mooring. PloS ONE. https://doi.org/10.1371/journal.pone. 0022522	2011	MBARI	Technical development / Proof of Concept	Prokaryotic (total RuBisCo and Synechococ cus)	1G? ESP. Moored	Here RT monitorin g for 28 days every 12 minutes with qPCR. 1L filtered amd 0.5 mL lysate used for	(samples for Ottesen et al collected in same deplyom ent)	DNA extraction and RT- qPCR (Proof of concept). Also nutrient sensor and fluoromete r	ESP commerciall y available (but likely not RT- qPCR module, developed at Lawrence Livermore Nat Lab.	-	First successful proof of concept of DNA extraction and RT- qPCR underwate r, using algal bloom in Monterrey Bay



Ottesen et al. (2011) Metatranscriptomic analysis of autonomously collected and preserved marine bacterioplankton. ISMEJ. http://doi.org/10.1038/ismej.2011.70	2011	MIT (MA, USA)	Metatranscript omic time series (weekly)	Prokaryotic diversity	1G?-ESP from MBARI. Moored	extractio n 5 filtered samples	RNALate r	Not used	ESP commerciall y available	Metatran scriptomi cs	Temporal variation of plankton metatransc riptome
Pargett et al. (2013) Deep water instrument for microbial identification, quantification, and archiving. Proceedings of 2013 OCEANS - San Diego. https://doi.org/10.23919/OCEANS.2 013.6741066	2013	MBARI	Technical development / Proof of Concept	Prokaryotic spp. and total abundance	Deep-ESP (benthic lander)	Deep-sea version of ESP operating to 4000m. Filtering and on- device molecula r assays	Not specified	RT-qPCR (?) and SHA	Developed in-house. Research use only (so far?)	-	Deployed at Axial Seamount Hydrother mal Emissions Study (ASHES) and used for sample collection an ondevice assays (unclear which)
Seegers et al. (2015) Subsurface seeding of surface harmful algal blooms observed through the integration of autonomous gliders, moored environmental sample processors, and satellite remote sensing in southern California. Limnol Oceanogr. https://doi.org/10.1002/lno.10082	2015	UCLA and MBARI collabor ation	Temporal monitoring of algal blooms / Proof of concept	HAB spp.	Moored ESPs at 10m depth, AUV monitoring of chlorophyll in 4D, and satellite	2 ESPs used for continou s monitorin g		SHA and ELISA	Commerciall y available ESPs (MBARI) and AUVs used	-	Indicated importance of subsurface population st to source for "seeding" surface Pseudo-

					remote sensing						nitzschia HABs in S California.
Pargett et al. (2016) Development of a mobile ecogenomic sensor. Proceedings of OCEANS 2015 - MTS/IEEE Washington. https://doi.org/10.23919/OCEANS.2 015.7404361	2016	MBARI	Technical development	(depends on configuratio n)	2G-ESP	Continou s RT for up to 3 month, max depth 50m	100+ pucks but only 3 for storing filters (?)	SHA and Immunoso rbent assays (cELISA; for toxins) w ready to use assays for specific HABs	Commerciall y available from McLane Labs and used in routine monitoring in the US: https://mclan elabs.com/e nvironmenta l-sample-processor/	-	-
Yamahara (2019) In situ Autonomous Acquisition and Preservation of Marine Environmental DNA Using an Autonomous Underwater Vehicle. Front Mar Sci. https://doi.org/10.3389/fmars.2019.0 0373	2019	MBARI	Benchmarking of eDNA filter preservation in ESP	Range of microbial to macro (fish) spp.	3G-ESP mounted on LR-AUV	15 x 1L ESP samples (1h each)	RNALate r	Not used	3G-ESP still not commercial (?)	qPCR of ESP and traditiona lly collected samples	No significant differences in eDNA densities observed between ESP and traditionall y collected
Ribeiro et al. (2019) Development of an autonomous biosampler to capture in situ aquatic microbiomes. PloS ONE, https://doi.org/10.1371/journal.pone. 0216882	2019	Portuge se consorti um: CIIMAR , INESC TEC,	development	Prokaryotic and phytoplankt on	eDNA sampling by pumping and filtering with the developed IS-ABS field prototype	2L samples. Distinct size fractions. Unclear how many	Unclear	No	In developmen t	Metabarc oding with both autonom ously and manually	

		and others				samples (0.2 uM or custom)				collected sample	
Zhang et al. (2020) Persistent Sampling of Vertically Migrating Biological Layers by an Autonomous Underwater Vehicle Within the Beam of a Seabed-Mounted Echosounder. IEE J Ocean Eng. https://doi.org/10.1109/JOE.2020.29 82811	2020	MBARI	Proof of concept of acuoustics guided eDNA sampling	Invertebrats	3G ESP mounted on LR-AUV	24 samples taken (out of 60)	RNALate r	acoustic modem	3G-ESP still not commercial (?)		
Hansen et al. (2020) Remote, autonomous real-time monitoring of environmental DNA from commercial fish. Sci Rep, https://doi.org/10.1038/s41598-020- 70206-8	2020	DTU Aqua (Denm ark)	Evaluation of ESP monitoring of fish	4x commercial fish spp.	2G-ESP on land, with pump, in large mesocosm	Continou s RT, 3x1L samples @ .2 uM (may be too little vol.)	-	RT-qPCR	ESP commerciall y available	qPCR validation	Only the most abundant species (mackarel) was detected consistentl y with enough accuracy (not only due to ESP)
Sepuldiva et al. (2020) Robotic environmental DNA bio-surveillance of freshwater health. Sci Rep, https://www.nature.com/articles/s41 598-020-71304-3	2020	US Geol. Survey	Proof of concept for freshwater	Pathogen and invasive fish spp.	2G (?) ESP on land with pump	1L samples	RNALate r	-	ESP commerciall y available	qPCR (from stored samples instead of on ESP. Why?)	Detects equally well but not better in spite of more samples so less sensitive. Still adventago us due to

											reduced effort. A later article also takes into account env parameter s and eDNA persistenc e / distribution modelling
Knapik et al. (2020) Metatranscriptomic Analysis of Oil- Exposed Seawater Bacterial Communities Archived by an ESP. Microorganisms. https://www.mdpi.com/2076- 2607/8/5/744	2020	NORC E (Norwa y)	Mesocosm / indicator identification	env. MRNA	2x 2GESP w oil exposure mesocosm	7x 0.7L samples @ .2 uM	RNALate r	-	ESP commerciall y available	Metatran scriptomi cs and 16S metabarc oding	
Tang et al. (2020) New insights into the distributions of nitrogen fixation and diazotrophs revealed by high-resolution sensing and sampling methods. The ISME journal. Doi: 10.1038/s41396-020-0703-6	2020	Nationa I Oceano graphy Centre (NOC)	Description of distribution of nitrogen fixation and diazotrophs	Prokaryotes	Robotic Cartridge Sampling Instrument —RoCSI	High- frequenc y filtering of between 1.5-4L of seawater	RNALate r		Don't know if it is sold. It is being used in the frame of iAtlantic and TechOceans projects.	RT- qPCR and metabarc oding	



Zhang et al. (2021) A system of coordinated autonomous robots for Lagrangian studies of microbes in the oceanic deep chlorophyll maximum. Science Robotics. http://doi.org/10.1126/scirobotics.ab b9138	2021	MBARI	Multi-robot monitoring system proof of concept	Prokaryotic diversity	LR-AUV ("Aku") w 3G-ESP for DCM sample collection at 260m	0.2 + 0.45 +5 uL filters (1.6L during 1h)	RNALate r	ChIA, nutrients	3G-ESP still not commercial (?)	Metabarc oding	"Deployed in the N Pacific Ocean within the core of a cyclonic eddy, this coordinate d system autonomo usly captured fundament al characteris tics of the in situ DCM microbial community in a manner not possible previously"
Moore et al. (2021) An Autonomous Platform for Near Real-Time Surveillance of Harmful Algae and Their Toxins in Dynamic Coastal Shelf Environments. J Mar Sci Eng. https://doi.org/10.3390/jmse9030336	2021	MBARI, NOAA, etc.	HAB monitoring proof of concept	HAB spp.	Moored ESP	Continou s (up to 7 weeks)		SHA: 7 spp. Of HABs	ESP commerciall y available	-	Possible connection bloom formation – nutrients-wind-forced coastal-trapped waves.



Formel et al. (2021) Subsurface automated samplers for eDNA (SASe) for biological monitoring and research. HardwareX. https://doi.org/10.1016/j.ohx.2021.e0 0239	2021	NOAA, Uni. Of Miami, Missisi pi State Uni.	Technical specs for automated open source low cost water sampler	(sampling only)	eDNA sampling by pumping and filtering	Down to 50 m (shallow only) and up to 4 samples but for a price of <300€	DNAgard	No	Freely available speces (but not built?)	qPCR, dPCR, metabarc oding	-
Flanigan et al. (2021) Proc from OCEANS 2021 San Diego, https://doi.org/10.23919/OCEANS44 145.2021.9705708	2021	SeaSat ellites (USA), Scripps institute	Technical development	(depends on configuratio n)	Programma ble surface water AUV with solar power	6 individual pumps, for one sampel each. Does not filter but collects up to 1L /sample	No	Not currently	Commerciall y available (or soon) from SeaSats	Both filtering and molecula r	-
Yoerger et al. (2021) A hybrid underwater robot for multidisciplinary investigation of the ocean twilight zone. Sci Robotics. https://doi.org/10.1126/scirobotics.a be1901	2021	Woods Hole, MBARI, Stanfor d	Technical development report for mesopelagic AUV. ROV for positoning	(depends on configuratio n)	eDNA sampling by pumping and filtering	Down to 1000 m depth able to track diel migrators . Up to 12 samples	RNALate r?	-	In developmen t	-	https://ww w.whoi.ed u/what-we- do/explore/ underwate r- vehicles/a uvs/mesob ot/
Truelove et al. (2022) Expanding the temporal and spatial scales of environmental DNA research with autonomous sampling. Env DNA. https://doi.org/10.1002/edn3.299	2022	MBARI (CA, USA)	Proof of concept / benchmarking	Microbial to macro (fish) diversity	ESP (3G- ESP) mounted on long range AUV (Tethtys?)	1L filtering at 0.2 uM Millipore (slowly, "sipping")	Flushed with N2, then in RNALate r. Max 60 samples	Not used in this study but see below for 2G ESP	3G-ESP and LR-AUV developed in-house at MBARI. Reasearch use so far (?)	Metabarc oding (12S, 16S, 18S, COI)	Results were comparabl e to samples taken from boat with Niskin bottle concurrentl

											y. Some differences may be explained by cells not lysing as with vacuum pump
Govindarajan et al. (2022). Improved biodiversity detection using a large-volume eDNA sampler with in situ filtration and implications for marine eDNA sampling strategies. Deep-Sea Research I. doi: 10.1016/j.dsr.2022.103871	2022	Woods Hole (and others)	Evaluation of biodiveristy detection by large-volume (40-60L) eDNA sampler compared to CTDs (2L)	Global diversity (v9-18S rRNA)	eDNA sampling by pumping and filtering	12 samples of 40-60L collected between 20-400 m depth (but can go deeper). Filters seawater at a rate of 2 l/min.	No	Machine-vision monochro me stereo cameras, color camera, and high-sensitivity radiometer (in the AUV)	No information in the paper, but Yoerger (developer of Mesobot AUV; Yoerger et al. 2021) is co-author here.	Metabarc oding of autonom ously and CTD-collected samples	The higher the seawater liters filtered the higher the diversity detected. They detected 66% more diversity filtering 40-60L using the large-volume eDNA sampler in a the Mesobot AUV than filtering only 2L using the CTD.
https://dartmouthocean.com/product s/edna-sampler	-	Dartmo uth Ocean Techno	Commercial product	(depends on configuratio n)	eDNA sampling by pumping and filtering	Up to 9 samples, max 20 m depth,	RNALate r	Flurometer (optional)	Commerciall y available	qPCR, dPCR, metabarc oding	-

The JERICO-S3 project is funded by the European Commission's H2020 Framework coordinator: Ifremer, France.

	logies Inc. (Canad a)				0.2 uM polycarb (or different)				
https://www.eomoffshore.com/environmentalsamplingprocessor	EOM - Offshor e	Website describing routine monitoring of HABs in the Gulf of Maine	HABs	2G ESP (moored)	Routine near- realtime monitorin g of HABs	SHA or qPCR	Deployed for monitoring	-	





#### 4.B - Conclusion

#### 4.1. Synthesis of main conclusion

The table showcases examples of developments and applications of devices for DNA sampling and/or analysis. This table will set the basics for future discussion and for the preparation of a review/synthesis document that will be shared with the relevant agents within and outside the consortium in form of a technical paper or a manuscript submitted for publication.

## 4.2. Next steps (work plan)

The table will be contrasted with the relevant scientist and end-users so that it is kept up to date. Additionally, Naiara Rodriguez-Ezpeleta has been invited as expert to the Marine Omics Instrumentation and Technology Workshop taking place October 10th - 12th, 2023 at the Monterey Bay Aquarium Research Institute (MBARI), whose goal is to survey the technology landscape for ocean deployable biomolecule sampling and sensing instrumentation by convening technology innovators. The workshop is aimed at catalyzing instrument development through discussions regarding the challenges and obstacles associated with semi-autonomous to autonomous, deployable instrumentation developed for omics based sample collection, processing and in-situ analysis. To realize and attain the workshop objectives we are promoting a non-competitive and open dialogue among the participants with the aim of accelerating the progress of the field.

This workshop (<a href="https://sites.google.com/mbari.org/moti-workshop/home">https://sites.google.com/mbari.org/moti-workshop/home</a>) will be an opportunity for knowledge sharing and community building of which JERICO-S3 will benefit as contributor to the roadmaps that will be defined as a result.